## TA16

## series



## Product Segments

## - Care Motion <br> - Comfort Motion <br> - Ergo Motion - Industrial Motion

TiMOTION's TA16 series linear actuator is similar to the TA2 linear actuator, but is specifically designed for low-noise applications where a compact linear actuator is needed. It is available with optional IP66 protection and Hall sensors for position feedback. Certificates for the TA16 include IEC60601-1, ES60601-1, IEC60601-1-2, UL962, and EMC.

## General Features

Max. load
Max. speed at max. load
Max. speed at no load
Retracted length
IP rating
Certificate

## Stroke

Output Signals
Options
Voltage
Color
Operational temperature range
at full performance
With very low noise, small size for easy installation
Suitable for patient hoist application

Drawing

Dimensions
without Output Signal
or with Hall Sensors
(mm)


Dimensions with POT
(mm)


Load and Speed

| CODE | Load (N) |  | Self Locking Force (N) | Typical Current (A) |  | Typical Speed (mm/s) |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Push | Pull |  | No Load 32V DC | With Load 24V DC | No Load 32V DC | With Load 24V DC |
| Motor Speed (3800RPM, Duty Cycle 10\%) |  |  |  |  |  |  |  |
| A | 2500 | 2500 | 2500 | 1.7 | 2.6 | 5.2 | 3.0 |
| B | 2000 | 2000 | 2000 | 1.7 | 2.6 | 8.3 | 4.7 |
| C | 1500 | 1500 | 1500 | 1.7 | 2.6 | 11.9 | 7.0 |
| D | 1000 | 1000 | 1000 | 1.7 | 2.6 | 17.7 | 10.3 |
| E | 500 | 500 | 500 | 1.7 | 3.5 | 58.2 | 28.8 |
| Motor Speed (5200RPM, Duty Cycle 10\%) |  |  |  |  |  |  |  |
| G | 3500 | 2500 | 3500 | 2.0 | 4.7 | 11.0 | 6.2 |
| J | 2000 | 2000 | 2000 | 2.0 | 3.7 | 17.0 | 10.5 |
| K | 1500 | 1500 | 1500 | 2.0 | 3.5 | 23.5 | 13.5 |
| L | 4500 | 2500 | 4500 | 2.0 | 5.0 | 9.5 | 4.9 |

## Note

1 \#G_When pull load > 2500N, please discuss with engineer.
2 Please refer to the approved drawing for the final authentic value.
3 This self-locking force level is reached only when a short circuit is applied on the terminals of the motor. All the TiMOTION control boxes have this feature built-in. The self-locking force is a minimum value and can be actually higher.

4 The current \& speed in table are tested with 24 V DC motor. With a 12 V DC motor, the current is approximately twice the current measured in 24 V DC. With a 36 V DC motor, the current is approximately two-thirds the current measured in 24 V DC. With a 48 V DC motor, the current is approximately half the current measured in 24 V DC. Speed will be similar for all the voltages.

5 The current \& speed in table and diagram are tested with TiMOTION control boxes, and there will be around $10 \%$ tolerance depending on different models of the control box. (Under no load condition, the voltage is around $32 \mathrm{~V} D \mathrm{C}$. At rated load, the voltage output will be around 24 V DC)

6 Without load, noise level $\leq 56 \mathrm{dBA}$ (by TiMOTION test standard, ambient noise level $\leq 36 \mathrm{dBA}$ ).
7 Standard stroke: Please refer to the table below.

| CODE | Load (N) | Min Stroke (mm) | Max Stroke (mm) |
| :--- | :--- | :--- | :--- |
| E | $\leq 500$ | 38 | 600 |
| D | $\leq 1000$ | 20 | 600 |
| C, K | $\leq 1500$ | 20 | 500 |
| B, J | $\leq 2000$ | 20 | 450 |
| A | $\leq 2500$ | 20 | 400 |
| G | $\leq 3500$ | 20 | 300 |
| L | $\leq 4500$ | 20 | 300 |

## Performance Data (24V DC Motor)

Motor Speed (3800RPM, Duty Cycle 10\%)

Speed vs. Load


Current vs. Load


Speed vs. Load


Current vs. Load


TA16
Version: 20230914-P

| Voltage | $1=12 \mathrm{~V} \mathrm{DC}$ | $3=36 \mathrm{~V} \mathrm{DC}$ | $5=24 \mathrm{~V} \mathrm{DC} PTC$, | $8=48 \mathrm{~V} \mathrm{DC} PTC$, |
| :--- | :--- | :--- | :--- | :--- |
|  | $2=24 \mathrm{~V} \mathrm{DC}$ | $4=48 \mathrm{~V} \mathrm{DC}$ | $6=12 \mathrm{~V} \mathrm{DC} PTC$, |  |

## Load and Speed See page 3

| Stroke (mm) | See page 3 |
| :---: | :---: |
| Retracted Length (mm) | See page 7 |
| Rear Attachment (mm) <br> See page 8 | $1=$ Aluminum, U clevis, width 6.0 , depth 12.2 , hole 6.4 , one piece casting with gearbox <br> 2 = Aluminum, U clevis, width 6.0, depth 12.2, hole 8.0, one piece casting with gearbox <br> $3=$ Aluminum, U clevis, width 6.0 , depth 12.2 , hole 10.0 , one piece casting with gearbox <br> $B=$ Aluminum, $U$ clevis, width 6.0 , depth 12.2 , hole 10.2 , one piece casting with gearbox, with plastic $T$-bushing (black), for weather resistant application |
| Front Attachment (mm) <br> See page 8 | $\left.\begin{array}{lc}1=\text { Aluminum, slotless, hole } 6.4 & 6=\text { Aluminum, U clevis, width 6.0, depth } 13.0 \text {, hole } 10.0 \\ 2=\text { Aluminum, slotless, hole } 8.0 & \text { B = Aluminum, slotless, hole 10.2, with plastic T-bushing } \\ \text { (black), for weather resistant application }\end{array}\right\}$= Aluminum, slotless, hole 10.0 Aluminum, U clevis, width 6.0, depth 13.0, hole 6.4 <br> C = Steel, U clevis, width 6.0, depth 13.0, hole 10.2,  <br> 5 = Aluminum, U clevis, width 6.0, depth 13.0, hole 8.0 with plastic T-bushing (black), for weather resistant <br> application |
| Direction of Rear Attachment (Counterclockwise) | $1=90^{\circ} \quad 2=0^{\circ}$ |

See page 9

| IP Rating | $1=$ Without | $3=1$ P66 | $6=1$ P66M |  |
| :---: | :---: | :---: | :---: | :---: |
|  | 2 = IP54 | $5=$ IP66W |  |  |
| Function of Limit Switches <br> See page 9 | $1=$ Two micro switches cut off the actuator at end of stroke <br> $2=$ Two micro switches cut off the actuator at end of stroke + third one in between sends signal <br> 3 = Two micro switches send signal at end of stroke <br> 4 = Two micro switches send signal at end of stroke + third one in middle sends signal |  |  |  |
| Special Function of Spindle Set | $\begin{aligned} & 0=\text { Without (Standard) } \\ & 1=\text { Safety nut } \end{aligned}$ | 2 = Standard push only <br> 3 = Standard push only + safety nut |  |  |
| Output Signal | $\begin{aligned} & 0=\text { Without } \\ & 1=\text { Pot. } \end{aligned}$ | $N=$ NPN Hall sensor * 2 |  |  |
| Connector <br> See page 9-10 | $\begin{aligned} & 1=\text { DIN } 6 P, 90^{\circ} \text { plug } \\ & 2=\text { Tinned leads } \\ & 4=\text { Big 01P, plug } \end{aligned}$ | $\begin{aligned} & C=Y \text { cable (For di } \\ & E=\text { Molex 8P, plug } \\ & F=\operatorname{DIN} 6 P, 180^{\circ} p \end{aligned}$ | stem, water proof, anti pull) | $\mathrm{G}=$ Audio plug |
| Cable Length (mm) | $\begin{aligned} & 0=\text { Straight, } 100 \\ & 1=\text { Straight, } 500 \\ & 2=\text { Straight, } 750 \end{aligned}$ | $\begin{aligned} & 3=\text { Straight, } 1000 \\ & 4=\text { Straight, } 1250 \\ & 5=\text { Straight, } 1500 \end{aligned}$ | $\begin{aligned} & 6=\text { Straight, } 2000 \\ & 7=\text { Curly, } 200 \\ & 8=\text { Curly, } 400 \end{aligned}$ | B $\sim H=$ For direct cut system See page 9 |
| Brake | $0=$ Without | 1 = Motor brake |  |  |
| Load Type | T = Push | $P=$ Pull |  |  |

## Color

$0=$ Silver grey
3 = Glittering black, for weather resistant application

## TA16 Ordering Key Appendix

## Retracted Length (mm)

1. Calculate $A+B+C+D+E=Y$
2. Retracted length needs to $\geq$ Stroke $+Y$

## A. Rear / Front Attach.

| Front <br> Attach. | Rear Attach. |
| :--- | :--- |
| $\mathbf{1 , 2 , 3}$ | $1,2,3, B$ |
| B | +112 |
| $\mathbf{4 , 5 , 6 , \mathbf { C }}$ | +115 |

## C. Load V.S. Spindle Functions

Spindle Load \& Speed Type
Functions A, B, C, D, E, J, K

```
G, L
```

0

| $\mathbf{1}$ | +10 | +5 |
| :--- | :--- | :--- |
| $\mathbf{2}$ | +2 | +2 |
| $\mathbf{3}$ | +12 | +7 |

## B. Load V.S. Stroke

| Stroke (mm) | Load \& Speed Type |  |
| :---: | :---: | :---: |
|  | A, B, C, D, E, J, K | G, L |
| 20~150 | - | +13 |
| 151~200 | +8 | +21 |
| 201~250 | +8 | +21 |
| 251~300 | +13 | +26 |
| 301~350 | +13 | +26 |
| 351~400 | +18 | +31 |
| 401~450 | +23 | +36 |
| 451~500 | +28 | +41 |
| 501~550 | +33 | +46 |
| 551~600 | +38 | +51 |

## D. Output Signals

CODE
0, 4, 5
$1+36$
E. IP Rating

CODE
1, 2, 3, 5
$6 \quad+5$

## Rear Attachment (mm)

1 = Aluminum, U clevis, width 6.0, depth 12.2, hole 6.4, one piece casting with gearbox

2 = Aluminum, U clevis, width 6.0, depth 12.2, hole 8.0, one piece casting with gearbox

12.2

12.2

3 = Aluminum, U clevis, width 6.0, depth 12.2 , hole 10.0, one piece casting with gearbox

12.2
$B=$ Aluminum, $U$ clevis, width 6.0 , depth 12.2, hole 10.2, one piece casting with gearbox, with plastic T-bushing (black), for weather resistant application


## Front Attachment (mm)

1 = Aluminum, slotless, hole 6.4
$\varnothing 6.4$

$5=$ Aluminum, U clevis, width 6.0, depth 13.0, hole 8.0

$2=$ Aluminum, slotless, hole 8.0
$\varnothing 8$

$6=$ Aluminum, U clevis, width 6.0, depth 13.0, hole 10.0


3 = Aluminum, slotless, hole 10.0

$B=$ Aluminum, slotless, hole 10.2, with plastic T-bushing (black), for weather resistant application


4 = Aluminum, U clevis, width 6.0, depth 13.0, hole 6.4


C = Steel, U clevis, width 6.0, depth 13.0, hole 10.2, with plastic T-bushing (black), for weather resistant application


## TA16 Ordering Key Appendix

## Direction of Rear Attachment (Counterclockwise)

$1=90^{\circ}$
$2=0^{\circ}$


## Function of Limit Switches

## Wire Definitions

| CODE | Pin |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 1 (Green) | 2 (Red) | $\bigcirc$ (White) | 4 (Black) | 5 (Yellow) | 6 (Blue) |
| 1 | extend (VDC+) | N/A | N/A | N/A | retract (VDC+) | N/A |
| 2 | extend (VDC+) | N/A | middle switch pin $B$ | middle switch pin A | retract (VDC+) | N/A |
| 3 | extend (VDC+) | common | upper limit switch | N/A | retract (VDC+) | lower limit switch |
| 4 | extend (VDC+) | common | upper limit switch | medium limit switch | retract (VDC+) | lower limit switch |

## Connector


$C=Y$ cable (For direct cut system, water proof, anti pull)


Cable Length for Direct Cut System (mm)

| CODE | L1 | L2 | L3 |
| :--- | :--- | :--- | :--- |
| B | 100 | 100 | 100 |
| C | 100 | 1000 | 400 |
| D | 100 | 2700 | 500 |
| E | 1000 | 100 | 100 |
| F | 100 | 600 | 1000 |
| G | 1500 | 1000 | 1000 |
| H | 100 | 100 | 1200 |

## TA16 Ordering Key Appendix

## Connector

$E=$ Molex 8P, plug

$F=$ DIN 6P, $180^{\circ}$ plug

$\mathrm{G}=$ Audio plug


## Terms of Use

The user is responsible for determining the suitability of TiMOTION products for a specific application.
TiMOTION products are subject to change without prior notice.

